

CLAIMS

What is claimed is:



1. An adjustment device; comprising:
 - a lifting mechanism having a lifting arm articulated to a component of a stationary supporting structure for moving the component between two end positions;
 - a rotary drive mechanism having an output member linked to the lifting arm; and
 - stationary support means, associated to the rotary drive mechanism, for at least partially absorbing a load moment exerted during movement of the component.
2. The adjustment device of claim 1 wherein the support means includes at least one support beam extending from one longitudinal side to another longitudinal side of the supporting structure.
3. The adjustment device of claim 1 wherein the support means includes two support beams extending from one longitudinal side to another longitudinal side of the supporting structure in spaced-apart parallel relationship, said rotary drive mechanism positioned between the support beams.

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- adjustment device of claim 2 wherein the at least one support means in one of a horizontal direction and vertical direction.
- adjustment device of claim 1 wherein the rotary drive mechanism includes a housing and a rotary drive fitted in the housing, said rotary drive including a fork head mounted to the housing of the rotary drive mechanism.
- adjustment device of claim 1 wherein the rotary drive mechanism includes a housing having a wall, and a rotary drive fitted in the housing, said support means including a rod received in aligned bores in the housing.
- adjustment device of claim 1 wherein the output member of the mechanism is form-fittingly connected to the lifting arm of the mechanism.
- adjustment device of claim 6 wherein the output member of the mechanism is a rotation part with a polygonal bore, said mechanism including two of said lifting arm and a crossbar having a bore for interconnecting the two lifting arms, said crossbar snugly fitting in the bore and extending through the bore.

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- ment device of claim 6 wherein the mechanism is a rotation part with a p m including a crossbar having oppos el rods of the component, said cro through the bore.
- ment device of claim 8, and further the rotary drive mechanism to the ce disposed on one of the lifting arm ve mechanism, said crossbar having hanism, said one end of the cross
- ment device of claim 1 wherein t a housing and a rotary drive fitted g stop means, mounted to one of the m and the lifting mechanism, for defini
- ment device of claim 11 wherein top member.

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Figure 1 consists of 14 subplots, labeled (a) through (n), arranged vertically. Each subplot shows a time series of a specific parameter over 10,000 time steps. The x-axis for all plots is 'Time' ranging from 0 to 10,000. The y-axis for each plot represents a different parameter, with scales varying between plots. The parameters shown are: (a) Average firing rate, (b) Average firing rate (with error bars), (c) Average firing rate (with error bars), (d) Average firing rate (with error bars), (e) Average firing rate (with error bars), (f) Average firing rate (with error bars), (g) Average firing rate (with error bars), (h) Average firing rate (with error bars), (i) Average firing rate (with error bars), (j) Average firing rate (with error bars), (k) Average firing rate (with error bars), (l) Average firing rate (with error bars), (m) Average firing rate (with error bars), and (n) Average firing rate (with error bars). The plots show a general downward trend in most parameters over time, with some parameters exhibiting more significant fluctuations than others.